

# SPECIFICATION

Product Name: Super Low Power CO<sub>2</sub> Sensor Module

Item No.: CM1106SL-NS

Version: V0.7

Date: November 5, 2021

## **Revision**

No.	Version	Content	Date
1	V0.1	First Edition	2020.12.07
2	V0.2	Update description of IIC protocol	2021.02.07
3	V0.3	Update description of IIC protocol	2021.03.01
4	V0.4	Update specification and register of IIC protocol	2021.03.04
5	V0.5	Update specification and IIC protocol description	2021.05.07
6	V0.6	Update packing information	2021.06.22
7	V0.7	Update single measurement description and IIC protocol information	2021.11.05



## Super Low Power NDIR CO<sub>2</sub> Sensor Module

## CM1106SL-NS



#### **Applications**

- HVAC industry
- Detecting units with battery operation
- Portable instruments

#### Description

CM1106SL-NS is super low power consumption, high performance NDIR battery-powered CO<sub>2</sub> sensor, which can be used to detect CO<sub>2</sub> concentration of indoor air by adopting advanced non-dispersive infrared (NDIR) technology. It is ideally suited for HVAC industry, detecting units with battery operation, portable instruments, etc.

#### Features

- NDIR technology with independent intellectual property
- Super low power consumption
- High accuracy, long-term stability, long life (>15 years)
- Temperature calibration within whole measurement range
- Auto-calibration, no need of maintenance
- Small size and compact structure, easy to install
- Wide supply voltage range enables variety of battery options.
- Adjustable measurement cycle by host
- ABC setting by host

#### **Working Principle**

The main components of an NDIR CO2 sensor are an infrared source, a sample chamber, a filter and an infrared detector. The infrared light is directed by the infrared source passing through the gas chamber towards the detector.



CO2 molecules inside the gas chamber will only absorb a specific wavelength of the light. The filter allows only the specific wavelength corresponded to pass through it. The detector measures the intensity of infrared light that is related to the intensity of CO2 and can be described through the Lambert-Beer's Law. The change in sensor signal reflects the change in gas concentration.

CM1106SL-NS Super Low Pow	CM1106SL-NS Super Low Power NDIR CO <sub>2</sub> Sensor Specification			
Target gas	Carbon dioxide (CO <sub>2</sub> )			
Operating principle	Non-dispersive infrared (NDIR)			
Measurement range	0-5000pm (Note 1)			
Working temperature	-10°C ~ 50°C			
Working humidity	0-95%RH (non-condensing)			
Storage temperature	-30°C ~ 70°C			
Storage humidity	0-95%RH (non-condensing)			
Accuracy	± (50ppm+5% of reading) (Note 2) ± (50ppm+3% of reading) (Note 3)			
Air pressure dependency	1% of reading / kPa @80-106KPa (sensor is calibrated at 101KPa)			
Power supply	DC 3.3V-5.5V			
Average working current	≪74uA (1 minute as measurement cycle) ≪37uA (2 minutes as measurement cycle)(Note 4)			
Measurement Setting	Default: single measurement mode (working mode A), reading output is without moving average (Adjustable by host) (Note 5)			
Dimensions	33.5x19.7x9.1mm			
Weight	5g			
Signal output	UART_TTL / IIC			
Life span	≥15 years			

**Note 1:** Sensor is designed to measure in the range 0~5000ppm. Nevertheless, exposure to concentrations below 400ppm may result in incorrect operation of ABC algorithm and shall be avoided for model with ABC ON.

**Note 2:** In normal IAQ applications, accuracy is defined with 10°C-35°C, 0-85%RH. ±(50ppm+5% of reading) could achieved under continuous power supply mode, with 4s as working cycle and moving average based on 24 data.

**Note 3:** In normal IAQ applications, accuracy is defined with  $10^{\circ}C-35^{\circ}C$ , 0-85%RH. When the sensor is under single measurement mode (controlled power supply by host), the sensor reading output is without moving average. The defined accuracy  $\pm$ (50ppm+3% of reading) is based on data moving average $\geq$ 5 and range of 400~2000ppm.

Note 4: See Figure 6 Average Current for more information under different working cycle.

**Note 5:** See more details in Sensor Working Mode. There are two working modes, working mode A and working mode B. Working mode A is single measurement mode (controlled power supply by host), while working mode B is continuous measurement mode. Default is working mode A. Command to set working mode is defined in UART and IIC protocol.

## **Dimensions and Connector**

#### 1. Dimensions (Unit mm, tolerance ±0.2 mm)



Figure 1

#### 2. I/O Connector Pin out

CON5				CON4		
Pin	Name	Description	Pin	Name	Description	
1	GND	Power supply input (GND)	1	EN	Power input enable (normal power supply at high level, power off at low level)	
2	VBB	Power supply input (3.3- 5.5V)	2	DVCC	Power supply output (2.8V)	
3	VDDIO	Communication supply input	3	RDY	To indicate the sensor data is ready, and the host could communicate (2.8V). (Effective to low level output)	
4	RX/SDA	UART-RX/IIC-SDA	4	COMSEL	Communication swift, high level or floating for UART, low level for IIC	
5	TX/SCL	UART-TX/IIC-SCL				

#### 3. The Function of PIN

Pin	Function				
VBB	Sensor power supply pin (3.3-5.5V)				
EN	Sensor power supply switch pin(2.8-5.5V)				

#### 4. The explanation of Pin working

VBB Status	EN Status	Sensor Status
0	L	No Working
3.3-5.5V	L	No Working
0	Н	No Working
3.3-5.5V	Н	Working

#### **Reference Circuit**

#### Application 1: UART\_TTL serial port output (Continuous Measurement Mode)



Figure 2

#### Application 2: UART\_TTL serial port output (Single Measurement Mode)













Figure 5

Note: electrical level of communication pins is the same as VDDIO pin.

#### **Power Consumption Chart**



#### CM1106SL-NS Average Current and Working Interval Graph

Blue Curve: light source work once in setting working intervals (T), every time work for 100ms.

The Graph shows the average current of CM1106SL-NS under single measurement mode (Working Mode A), the host shall control EN pin (or VBB pin) to control power supply of the sensor.

To get lower working current under the same scenario, Cubic could offer sensor type with 100ms working mode for light source. Under this mode, the average working current is 37uA @ two minutes' working interval. For sensor work with IIC communication with high SCL frequency, the power consumption might be different. For more information, please contact Cubic.

#### Working Sequential Chart (working mode A)





#### 1. Explanation of working sequential chart

The working mode of CM1106SL-NS is host-slave mode: CM1106SL-NS is a slave and it begins to work after getting EN and VBB pin high level and getting power from the host. After powering on for 500ms, the light source flashes for 100ms, and then MCU of CM1106SL-NS starts a calculation on measured CO2 concentration, the calculation takes 100ms, consider 30ms for communication, so in total one circle working time is around 730ms. Then the host could communicate with CM1106SL-NS when the RDY pin goes low level. After communication, the host will put EN pin to low level and the CM1106SL-NS is powered off and stops working.

#### 2. Explanation of working mode

Cubic Super Low Power NDIR CO2 Sensor CM1106SL-NS supports two working modes for measurement of CO2 concentration: single measurement mode (working mode A) and continuous measurement mode (working mode B).

#### Working mode A, single measurement mode

When in single measurement mode, the sensor works by waiting for the hosts command to measure. The host need to send a command sequence to trigger each measurement. After each measurement, EN pin need to be set to low power level. The reading output from the sensor is without moving average. The host could make moving average to get better stability and higher accuracy.

#### Working mode B, continuous measurement mode

When in continuous measurement mode, the sensor works at regular intervals (default setting 2 minutes). The host can read measurement after each measurement and does not need to send any command to trigger measurements. The host could set working intervals and set moving average to get better stability.



1. CM1106SL-NS is with default single measurement mode (working mode A).

Under this working mode, the working interval T = host setting working interval, the sensor works only one time during a working interval. There is no data moving average (the moving average data D=1).

2. When host send command to activate working mode B, the sensor will enter continuous measurement mode. The host could set Working Interval [T] \* and Data Moving Average [D] \*. Setting command is in UART protocol. The default working interval is 2 minutes.

[T] = Working Interval [D] = Data Moving Average [D], maximum value is 120.

#### **Description of Calibration**

CM1106SL-NS can support auto baseline calibration function (Auto Calibration is closed by default), the user could open the Auto Calibration function by command in protocol.

#### Auto Calibration:

Rough installing and influence of transportation might result in a reducing of sensor reading accuracy and baseline drift, sensor will correct the drift by the built-in self-correcting logic.

#### 1. Continuous Measurement Mode

When the host sends command to activate working mode B, the sensor will enter continuous measurement mode. Powering on the sensor for 7 days (7 days by default) continuously, it will record the lowest CO<sub>2</sub> concentration measurement value during the 7 days, which will be regarded as baseline (400ppm) when sensor do auto calibration after the 7 days working.

Remark: The sensor is with Auto Calibration closed by default.

#### 2. Single Measurement Mode

The sensor does not record working time or store readings for ABC in this mode, the host need to send command to the sensor to trigger this function, please refer to the communication protocol for details.

When the storing data reaches to calibration cycle\*48 times (default of calibration cycle is 7 days, so in single measurement mode the sensor will calibrate after 7\*48=336 times measuring), it will invoke the lowest CO<sub>2</sub>

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concentration measurement from the storing data, which will be regarded as baseline (400ppm) by the sensor and implement auto calibration.

#### Note:

1. If the sensor works in continuous measurement mode, please ensure the sensor is powered on during the complete one ABC working cycle, otherwise it cannot trigger the calibration.

In single measurement mode, CM1106SL-NS supports power-off storage, even if the power is off, the stored data is still retained, when the storing data reaches to <u>calibration cycle\*48</u> times, the sensor will implement auto calibration.
 In order to ensure the reading accuracy after auto calibration, please make sure the working environment of sensor can reach the outdoor fresh air level, that is to say, the CO<sub>2</sub> concentration of sensor can reduce to the outdoor air level (400ppm) during the ABC cycle.

4. Please contact with Cubic for more detailed auto calibration strategy.

5. If auto calibration environment cannot be ensured, then regular manual calibration is recommended, please refer to the communication protocol 4.2 or target calibration function in IIC protocol, implement calibration and set the CO2 concentration as 400ppm under fresh air environment.

#### **Product Installation**

1. In order to ensure airflow diffusion into the sensor inner, make sure the minimum distance between the area of waterproof filter and the other components is 1.5 mm, otherwise, quick response time of the sensor will be affected. **Reference as below:** 



Figure 8

To avoid the influence of stress on sensor, please soldering by hand as much as possible when mounting the sensor to the PCB.

#### Reference as below:



Figure 9

#### **UART Communication Protocol**

1. CM1106SL-NS supports UART communication protocol.

To meet the requirements from more designers, CM1106SL-NS is with two sets of UART communication protocol. Below information is one of the UART communication protocol (Protocol Version 1). If it is not suitable for designer to integrate, please contact <u>info@gassensor.com.cn</u> to request the other UART communication protocol.
 Customized communication protocol is also available, for more details, please contact Cubic by <u>info@gassensor.com.cn</u>.

#### **1. General Statement**

1). The data in this protocol is all hexadecimal data. For example, "46" for decimal [70].

2). Baud rate: 9600, Data Bits: 8, Stop Bits: 1, Parity: No, Flow Control: No.

3). [x x] for single-byte data (unsigned, 0-255); [x x] for double data (signed,-32768~+32767), high byte is in front of low byte. It is remark after "——".

4). All data is an integer and may have a (100, 10, 1)-fold correspondence with the actual display data (related to the specific instrument).

5). Sensor operation remains after power off

#### 2. Format of Serial Communication Protocol

Sending format of test software:

Start Symbol	Length	Command	Data1	Data n.	Check Sum
HEAD	LEN	CMD	DATA1	 Data	CS
11H	XXH	XXH	XXH	 XXH	XXH

#### Detail description on protocol format:

Protocol Format	Description	
Start Symbol Sending by test software is fixed as [11H], module response is fixed as [16H]		
Length Length of frame bytes= data length +1 (including CMD+DATA)		
Command	Command	
Data	Data of writing or reading, length is not fixed	
Check Sum	Cumulative sum of data = 256-(HEAD+LEN+CMD+DATA)%256	

#### 3. Command Table of Serial Protocol

Item No.	Function Name	Command
1	Read measured result of CO <sub>2</sub>	0x01
2	Calibration of CO <sub>2</sub> concentration	0x03
3	ABC parameter check	0x0F
4	ABC parameter set	0x10
5	Read software version	0x1E
6	Read the serial number of the sensor	0x1F

7	Set /check sensor measurement period and number of smoothing data	0x50
8	Set / check sensor working status	0x51
9	Sensor ABC calibration data store	0x11

#### 4. Detail Description of UART Protocol

4.1 Read Measured Result of CO<sub>2</sub>

Send: 11 01 01 ED Response: 16 05 01 DF1- DF4 [CS] Function: Read measured result of CO<sub>2</sub> (Unit: ppm)

#### Note:

CO<sub>2</sub> measured result = DF1\*256+DF2 DF3, DF4 is reserved

Example: Response: 16 05 01 02 58 00 00 8A Explanation: Hex is converted to decimal: 02 is 02; 58 is 88  $CO_2$  concentration =02\*256+88 = 600ppm

#### 4.2 Calibration of CO<sub>2</sub> Concentration

Send: 11 03 03 [DF1] [DF2] [CS] Response: 16 01 03 [CS] Function: Calibration of CO<sub>2</sub> concentration

#### Note:

1. Calibration target value = DF1\*256+DF2 Unit: PPM, range (400-1500ppm)

2. Before calibration, please make sure CO<sub>2</sub> concentration in current ambient is calibration target value. Keeping this CO<sub>2</sub> concentration for two 2 minutes, and then begin calibration.

3. Calibration command shall be sent AFTER at least 5s (not available for software version V0.09SL-NS1) power on (VBB connected and EN pin in high level continuously), otherwise the sensor will not implement calibration. **Example:** 

When need to calibrate  $CO_2$  concentration of the sensor to 600ppm, send command:11 03 03 02 58 8F Hex is converted to decimal: 02 is 02; 58 is 88,  $CO_2$  concentration =02\*256+88 = 600ppm

#### **4.3 ABC Parameter Check**

Send: 11 01 0F DFResponse: 16 07 0F [DF1] [DF2] [DF3] [DF4] [DF5] [DF6] [CS]Function: Sensor ABC parameter check, explanation of DF1~DF6 is the same as 4.4.

Example: Send: 11 01 0F DF Response: 16 07 0F 64 02 07 01 90 64 72

4.4 Open/Close ABC and Set ABC Parameter Send: 11 07 10 [DF1][DF2][DF3][DF4][DF5][DF6][CS] **Response:** 16 01 10 D9 **Function:** Sensor ABC parameter set

#### **Explanation:**

DF1: reserved, default 100 (0x64) DF2: open/close auto calibration (0: open; 2: close, the default is close) DF3: calibration cycle (1-10 optional, 7days is default) DF4 and DF5: The high and low baseline of calibration. (2 bytes), baseline of calibration=DF4\*256+DF5 DF6: reserved, default is 100 (0x64) Note: The default baseline of calibration is 400ppm, hex is converted to decimal: 01 is 01 and 90 is 144, so DF4=01 and DF5=90 by default.

4.4.1 Open ABC and Set Calibration Cycle

Send: 11 07 10 64 00 07 01 90 64 78 Response: 16 01 10 D9

**4.4.2 Close ABC** Send: 11 07 10 64 02 07 01 90 64 76 Response: 16 01 10 D9

#### 4.5 Read Software Version

Send: 11 01 1E D0 Response: 16 0C 1E [CH1].....[CH11] [CS] Function: Read software version

Note: Input software version number: [CHx] stand for software version by ASCII code.

#### Example:

When the sensor version is V0.04SL-N2, response data as follows: 16 0C 1E 56 30 2E 30 34 53 4C 2D 4E 32 00 5C

Note: When hexadecimal 20 is converted to ASCII code, the ASCII code is the blank space.

4.6 Read the Serial Number of the Sensor

Send: 11 01 1F CF
Respond: 16 0B 1F (SN1) (SN2) (SN3) (SN4) (SN5) [CS]
Function: Read the serial number of the sensor
Note: Output the serial number of the sensor. SNn is from 0 to 9999. The 20 bit number is formed by five integers.

#### Example:

Send: 11 01 1F CF Response: 16 0B 1F 00 00 02 11 03 8C 0A D3 00 08 39 Sensor serial number: 00000529090827710008

4.7 Set / Check Measurement Period and Number of Smoothed Data

Set: Send: 11 04 50 [DF1] [DF2] [DF3] [CS] Response: 16 01 50 [CS]

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Check: Send: 11 01 50 [CS]

Response: 16 04 50 [DF1] [DF2] [DF3] [CS]

#### **Description:**

Measurement period (s) period = DF1 \* 256 + DF2, unit s (range: 4s ~ 10min) Number of smoothed data = DF3

#### Example:

Set the sensor working intervals as 2 min and the number of smooth data as 15 Send: 11 04 50 00 78 0F 14 Note: The smoothing time is no longer than 30min. If the sensor measurement period is set to 2min, the maximum smoothed data number is 30(min) / 2(min) =15

#### 4.8 Set / Check Working Status

Set: Send: 11 02 51 [DF1] [CS] Response: 16 01 51 [CS] Check: Send: 11 01 51 [CS] Response: 16 02 51 [DF1] [CS] Description: DF1 = 0 single measurement mode (working mode A) DF1 = 1 continuous measurement mode (working mode B)

Example: Set to continuous power mode Send: 11 01 51 01 98

#### 4.9 Sensor ABC Calibration Storing Data

Send: 11 01 11 [CS] Response: 16 01 11 [CS]

Description: When the sensor is in the single measurement mode, the host needs to send an ABC calibration storing data command to the sensor, to not let the sensor perform ABC too often, Cubic advises to send the command every 30min (if power supply interval is less than 30 minutes), or after each time measurement (if the power supply interval is longer than 30 minutes).

### I<sup>2</sup>C Communication Protocol

#### 1. I<sup>2</sup>C settings

The sensor acts as a slave device on the  $I^2C$  bus.

#### Table 1: I<sup>2</sup>C settings

Parameter	Value	Description
Master/slave mode	Slave	Sensor will never initiate communication
Data rate	Up to 100kbit/s (standard mode)	
Addressing mode	7 bit	
Address range	1 – 7F	Original IIC address (7 bit) and default is 34, writing bit
		is 0, and reading bit is 1
		send 0X68 (original address + writing bit) to write
		send 0X69 (original address + reading bit) to read
Clock stretch	Yes	If sensor needs time to evaluate a received byte it will
		hold SCL low
SCL pull-up	10kΩ	
SDA pull-up	10kΩ	
SCL frequency	10kHz~100kHz	SCL frequency is generated by the master device
Writing time to EE	<25ms	Writing one register to sensors EEPROM can take up to
		25ms, if sensor is powered off when EEPROM write
		operations are ongoing it may result in corrupt
		parameters.

#### Note:

Communication sequence:







Figure 11. Writing to the sensor

## 2. I<sup>2</sup>C register map

I<sup>2</sup>C registers are categorized into two groups, which are Table 2 I<sup>2</sup>C read only registers and Table 3 I<sup>2</sup>C read/write registers.

Table 2: read only registers

Error Status	0X00	Reserved				
	0X01	Bit	Error description	Suggested action		
		0	Fatal error Indicates that initialization of analog front end failed	Try to restart sensor by power on/off. Contact the supplier		
		1~4	Reserved			
		5	Out of range Indicates that the measured concentration is outside the sensor's measurement range	Perform suitable CO2 calibration (zero, background or target calibration). Contact the supplier.		
		6~7	Reserved			
Reserved	0X02~0X05					
CO2 concentration	0X06	0X06 is high byte and 0X07 is low byte, the unit is ppm,				
	0X07	CO2 coi	ncentration=0X06*256+0	)X07		
Temperature	0X08	Chip temperature, T=0X08*256+0X09, unit °C x100.				
	0X09	For example, register value = 2223 means 22.23°C.				
Reserved	0X0A~0X0C					
Measurement count	0X0D	Counter incremented after each measurement, range ( - 255. The counter wraps around after the maximum				
Measurement cycle time	0X0E	Measurement cycle time shows current time in present measurement cycle, incremented every 2 seconds. For				
	0X0F	example, Measurement cycle time = 3 means 6 seconds has passed in current measurement cycle. Value is set to 0 when sensor starts a new				
CO2 concentration	0X10	0X10 is	high byte and 0X11 is lo	w byte, the unit is ppm,		
	0X11	CO2 coi	ncentration=0X10*256+0	)X11		
CO2 concentration	0X12	0X12 is high byte and 0X13 is low byte, the unit is ppm				
	0X13	CO2 co	ncentration=0X12*256+0	)X13		
CO2 concentration	0X14	0X14 is	high byte and 0X15 is lo	w byte, the unit is ppm,		
	0X15	CO2 co	ncentration=0X14*256+0	)X15		
Reserved	0X16~0X3F					

#### Table 3: read/write registers

Name	Register number / Address	Description		
Reserved	0X80			
Calibration Status	0X81	Bit		description
(Read only)		0~2 Reserved		served
		3	AB	C calibration
		4	Tar	get calibration
		5	Ba	ckground calibration
		6	Zer	ro calibration
		7	Re	served
Calibration	0X82	Command		Name and description
Command		0X7C02~ 0X7C04	1	Reserved
		0X7C05		Target calibration, calibration
				target needs to be set first
	0X83	0X7C06		Background calibration
		0X7C07		Zero calibration
Calibration Target	0X84	Calibration target u	sed b	by target calibration
	0X85	(0X820X83- 0X7C05 command). Need		command). Need to set target calibration
CO2 Value Override	0X86	Default value = 32767 (no override). If a value           than default is written to the register CO2 value           0x87 (LSB) set to this value after next measure		no override). If a value lower
	0X87			the register CO2 value will be alue after next measurement.
ABC Time	0X88	Time passed since last ABC calibration in the unit of		ABC calibration in the unit of
	0X89	half an hour, for instance 00 04 means 2 hours pa		e 00 04 means 2 hours passed
Reserved	0X8A-0X92			
Start Single	0X93	Writing 1 initiates a measurement if the sensor is		
Measurement		configured for singl	e me	asurement mode.
Reserved	0X94			
Measurement Mode	0x95	There are two mea	surer	ment modes to choose
(EE)		between. Value = 0	), con	tinuous measurement mode.
		Value = 1, single m	easu	rement mode (default).
Measurement Period	0X96	Measurement perio	od in	seconds (range from 2 to
(EE)		65534). Odd numb	ers w	ill be rounded up to nearest
	0X97	even number.		
		Note: Measurement period is only used in continuous		
		measurement mode		
Reserved	0X98~0X99			
ABC period (EE)	0X9A	Period for ABC cyc	od for ABC cycle in hours (range from 24 to 240).	
	0X9R	Default is 168 hour	s. AB	BC cycle is in unit of day, and
	0,000	ABC period=ABC c	;ycle*	24.
Reserved	0X9C~0X9D			

ABC Target (EE)	0X9E	Target value for	Target value for background and ABC calibrations (ppm CO2). Default value is 400 (400 ppm CO2).	
	0X9F	CO2). Delault v		
Reserved	0XA0~0XA4			
Meter control (EE)	0XA5	Bit	description	
		0	reserved	
		1	0: ABC enabled;	
			1: ABC disabled	
		2~7	reserved	
Reserved	0XA6			
MB/I <sup>2</sup> C address (EE)	0XA7	Sensor original value is 34. EEF	Sensor original address, range 1 – 7F (note1). Default value is 34. EEPROM mapped register.	
Reserved	0XA8~0XDF			

Note1: Not available for software version V0.09SL-NS1

#### 3. I<sup>2</sup>C Example on Cubic Testing Board

#### 3.1 Read measuring result:

Send: 68 06 00 02

No Response

Send: 69

Response: 04 EE

#### Note:

- 1. 68 is address + writing bit, 06 is starting register to be read/write; 00 is reading command to Cubic testing board, and 02 is byte digit need to be read, for other device setting method might be different.
- 2. The sensor will not response to the command "68 06 00 02".
- 3. 69 is address + reading bit, to read measurement result.
- 4. Response with 2 bytes 04 EE, CO<sub>2</sub> measuring result = (0x04 0xEE) hexadecimal = 1262 ppm.

#### 3.2 Set up continuous working mode

Send: 68 95 00 01 01

#### No Response

Note:

- 1. 68 is address + writing bit, 95 is starting register to be read/write, 00 is the data to be written to register; the first 01 is writing command to Cubic testing board, and the second 01 is byte digit need to be written, for other device setting method might be different.
- 2. The sensor will not response to the command "68 95 00 01 01".

#### **Packing Information**



Note: every 5 trays are packed by a plastic vacuum bag;

Sensor per Tray	Tray Qty	Sensor per	Carton Dimensions	Packing Material
75 pcs	15 layers	1125 pcs	W395 * L310 * H200	Anti-static PS

## **After-Sales Services and Consultancy**

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